



SCUDEM IV 2019
Problem B
Lincoln Memorial University

Timothy Taylor
Richard Bradley
Jonathan Perry
Coach: Timothy Clayton



Microgravity Movement

OBJECTIVES:

- Land a Probe on an Asteroid
- Determine Smallest Dimensions of Asteroid
- Develop a Method to Land at Predetermined Landing Spot
- Design a System to Move Probe on Asteroid



Method:

- Carrier Rocket is Launched into Space
- Rocket Orbits the Asteroid
- Probe is Deployed toward Asteroid
- Probe Uses Spring System to Travel



Lift-Off:

- Carrier Rocket is Launched
- Three-Stage-to-Orbit launch system is utilized
- $M \frac{dv}{dt} = v_{ex} \frac{dm}{dt}$ (momentum eq.)



Lift-Off:

When the function is integrated a constant exhaust velocity is achieved and we get that

$$v_f = v_i + v_{ex} \ln \left(\frac{M_i}{M_f} \right)$$

The formula given for a change in velocity is:

$$\Delta V = -c \ln \left[1 - \frac{(1-S)M_r}{(P+M_r)} \right]$$

with M_r equal to the mass of an engine, payload P , structural factor S , determined by the ratio of the rocket with fuel to the total mass of the rocket including the payload, and exhaust c , which will be called equation 1. $\Delta v = v_f - v_i, v_{ex} = -c$, $M_i = P + M_r$, and $M_f = P - SM_r$

This equation makes some basic assumptions in order for it to work properly.

If M_i is the mass of the i th stage, then it can be initially considered for the first stage that the rocket engine has mass M_1 and its payload has mass $M_2 + M_3 + A$. The second and third stages are handled similarly. Using equation 1 for ΔV and the mass of the third stage ($M_3 + A$) it is found that the velocity after the third stage is jettisoned will be

$$V_3 = c \ln \left[\frac{SM_3 + A}{M_3 + A} \right]$$

(1)



Lift-Off:

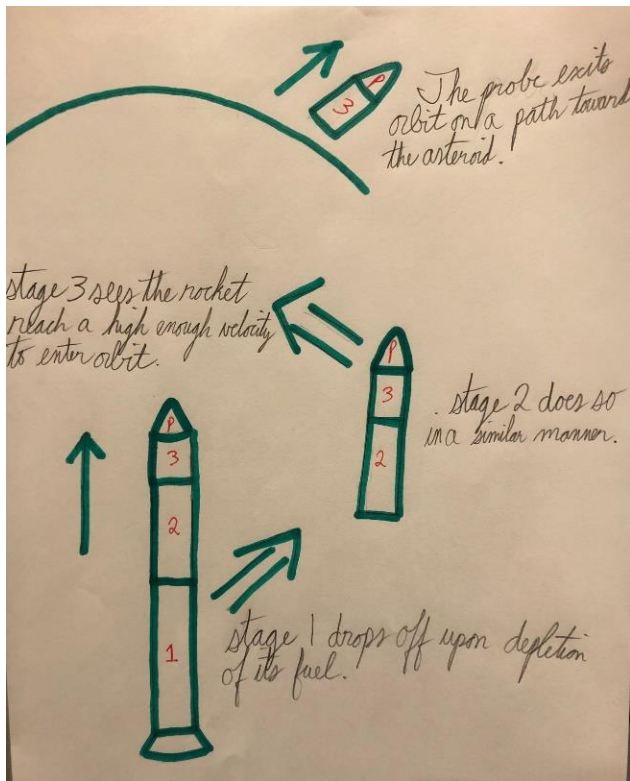
Using a similar process for the second and first stage it is possible to show that the velocity after all three stages have been jettisoned (equation 2) is:

$$v_f = c \left[\ln \left(\frac{M_1 + M_2 + M_3 + A}{SM_1 + M_2 + M_3 + A} \right) + \ln \left(\frac{M_2 + M_3 + A}{SM_2 + M_3 + A} \right) + \ln \left(\frac{M_3 + A}{SM_3 + A} \right) \right]$$

(1)



Rocket Launch Design





Orbital Motion:

- Carrier Rocket Orbits Asteroid

- Angular Velocity: $\dot{\vartheta} = \frac{\ell}{mr^2}$

- $\frac{d^2u}{d\vartheta^2} + u = -\frac{m}{\ell^2 u^2} F\left(\frac{1}{u}\right)$, $u = \frac{1}{r}$

- (3)



Probe Landing:

- Carrier Rocket Releases Probe
- Probe undergoes Free-Fall
- Newton's Law of Gravitation



Probe Landing:

- Free-Fall:

- $$\frac{d^2 x}{dt^2} = \mathcal{G}_A - \frac{A}{m} \frac{dx}{dt}$$

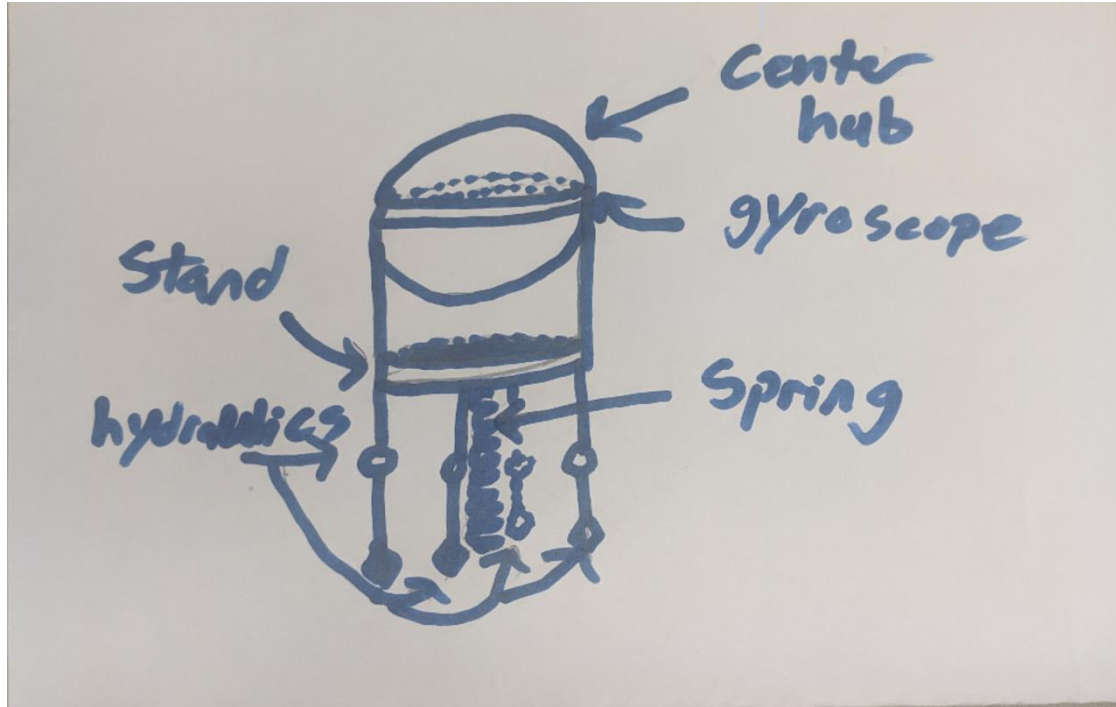
- Landing Oscillations Model:

- $$-mg = kx + m\ddot{x} - \mu m\ddot{x} + \sum \mathcal{b}_n [\cos\vartheta_n + \sin\vartheta_n] m \frac{d^2 x}{dt^2}$$

- (2)

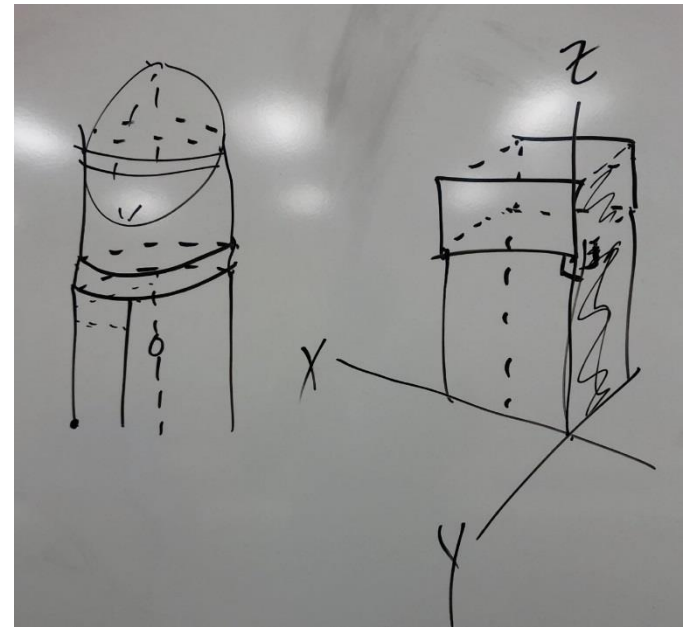
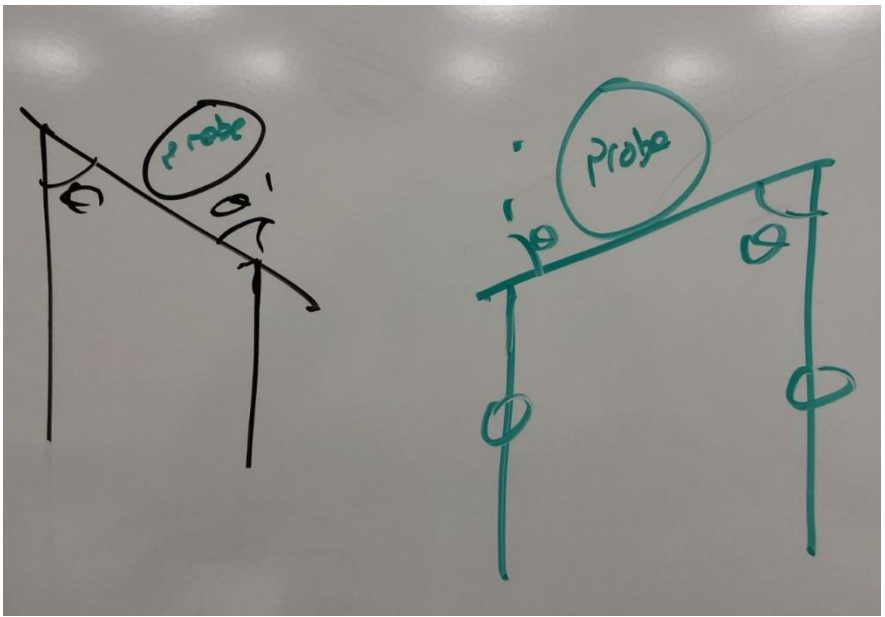


Probe Design





Probe Design





Landing Mechanics

- Probe Has a Rotatable Spring In the Event of Landing on Side.
- Gyroscope Used to Rotate Movable Spring into Position
- Low Gravity with Spring Shocks Protect Probe From Impact



Post-Land Travel:

- Spring is Positioned Using Gyroscope
- Probe is Propelled by Spring

- $-mg = kx + m\ddot{x} - \mu m\ddot{x} + \sum b_n [\cos\vartheta_n + \sin\vartheta_n] m \frac{d^2x}{dt^2}$

- Projectile Motion:

- $k(y_i - y_c)^2 + 2mgy_c = 2mgy_t + ky_t^2 + m\left(\frac{dx}{dt} + \frac{dy}{dt} + \frac{dz}{dt}\right)^2$



Additional Issue Question B #3

- Assume initial position of Probe = 0
- $\mathcal{P} = x(t) + y(t) + z(t)$
- $\frac{dP}{dt} = \frac{\delta x}{\delta t} \mathbf{i} + \frac{\delta y}{\delta t} \mathbf{j} + \frac{\delta z}{\delta t} \mathbf{k}$
- $K(y_i - y_c)^2 + 2mgy_c = 2mgy_f + K y_f^2 + m\left(\frac{\delta x}{\delta t} \mathbf{i} + \frac{\delta y}{\delta t} \mathbf{j} + \frac{\delta z}{\delta t} \mathbf{k}\right)^2$



Limitations

- Probe Linear Path to Asteroid
- Low Gravity on Asteroid Implies Low Acceleration
- Probe Landing in Unescapable Trench
- Spring Losing Elasticity from Impact
- Radius of Probe Must be Much Smaller than Asteroid's.
- Rocket Has Low Range Due to Linear Flight Path



Questions?

- Timothy.taylor02@Imunet.edu
- Richard.Bradley@Imunet.edu
- Jonathan.Perry@Imunet.edu



References

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- (2) Nagle, R. K., Saff, E. B., & Snider, A. D. (2019). *Fundamentals of differential equations*. Harlow, United Kingdom: Pearson Education Limited.
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- (4) Zill, D. G. (2013). *A First Course in Differential Equations with Modeling Applications, Tenth Edition / Dennis G. Zill*. Boston, MA: Brooks/Cole, Cengage Learning.



Thank you!